

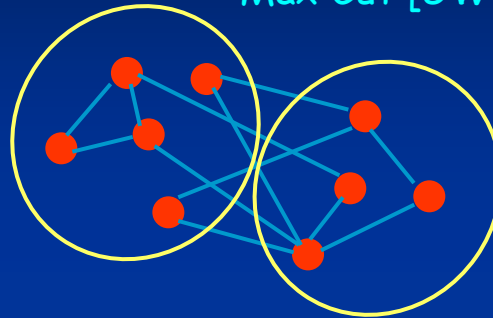
# A Combinatorial, Primal-Dual Approach to Semidefinite Programs

Satyen Kale  
Microsoft Research

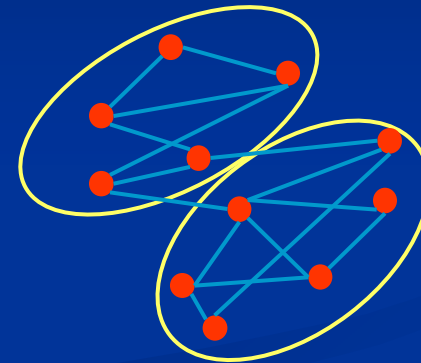
Joint work with  
Sanjeev Arora  
Princeton University

# The Ubiquity of Semidefinite Programming

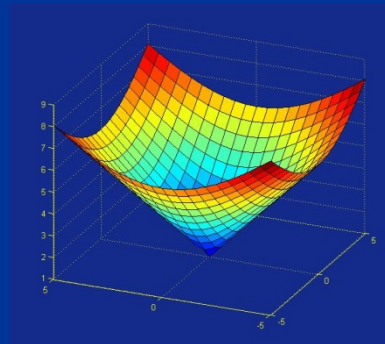
Max Cut [GW'95]



Balanced Partitioning [ARV'04]



$dx(t)/dt = Ax(t)$   
Control Theory



SDP

$(a \zeta \neg b) \wedge (\neg a \zeta c) \wedge (a \zeta b) \wedge (\neg c \zeta b)$

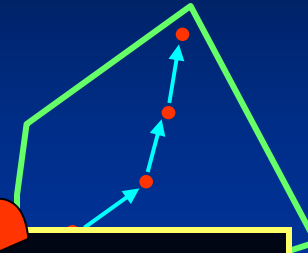
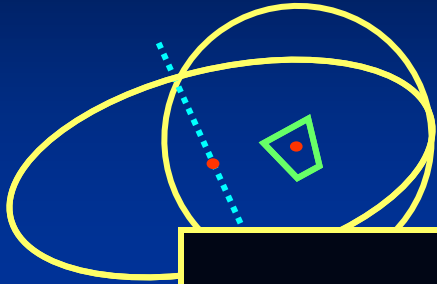
1 0 0 0 1 1 0 1

Constraint Satisfaction [ACMM'05]



Graph Coloring  
[KMS'98, ACC'06]

# Algorithms for SDP



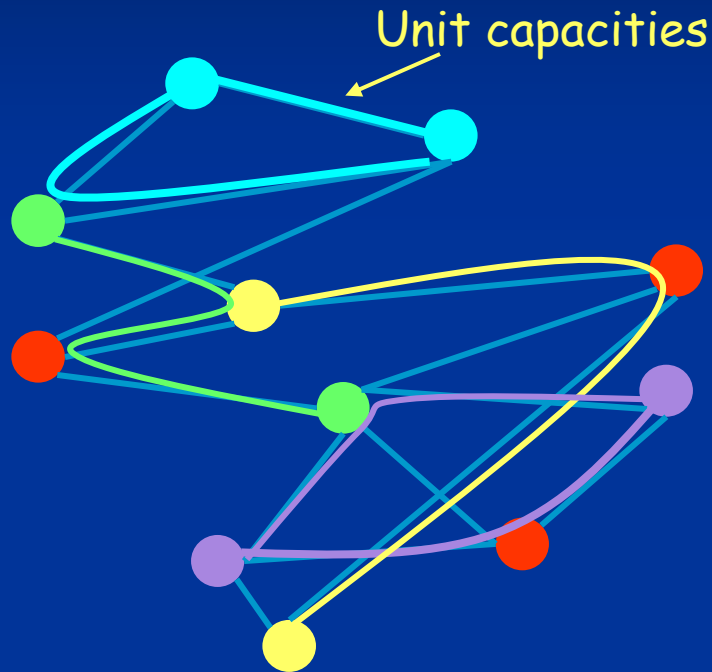
Ellipsoid  
•  $O(n^8)$  it

methods  
time

**MISSING**  
Combinatorial,  
Primal-Dual algorithms

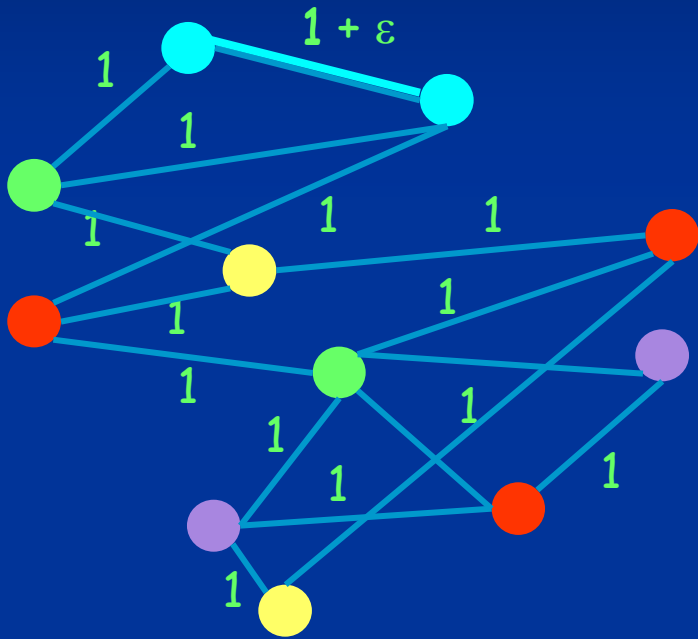
- Reduction to eigenvectors
- $\text{poly}(1/\varepsilon)$  dependence on  $\varepsilon$ , limits applicability (e.g. Sparsest Cut)

# Primal-Dual algorithms for LP: Multicommodity Flows



Objective: Maximize total flow,  
while respecting edge capacities

# Primal-Dual algorithms for LP: Multicommodity Flows



- Edge weights  $w_e = 1$
- Repeat until some  $e$  reaches capacity:
  - Find shortest path  $p$
  - Route  $\epsilon^2 / \log(m)$  flow on  $p$
  - Update  $w_e$  for all  $e \in p$  as
$$w_e \leftarrow w_e \cdot (1 + \epsilon)$$
- Output flow.

Thm [GK'98]: Stops in  $\tilde{O}(m)$  rounds with  $(1 - 2\epsilon) \cdot \text{OPT}$  flow. Total running time is  $\tilde{O}(m^2)$ .

# Primal-Dual algorithms for LP: Multicommodity Flows

1. Primal-Dual algorithm

2. Combinatorial

3. Multiplicative  
Weights Update Rule

- Edge weights  $w_e = 1$
- Repeat until some  $e$  reaches capacity:
  - Find shortest path  $p$
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Thm [GK'98]: Stops in  $\tilde{O}(m)$  rounds with  $(1 - 2\varepsilon) \cdot \text{OPT}$  flow. Total running time is  $\tilde{O}(m^2)$ .

- Starting point for our work:
  - Analogous primal-dual algorithms for SDP?
- Difficulties:
  - Positive semidefiniteness hard to maintain
  - Rounding algorithms exploit geometric structure (e.g. negative-type metrics)
  - Matrix operations inefficient to implement
- Our work: a generic scheme that yields fast, combinatorial, primal-dual algorithms for various optimization problems using SDP

# Our Results: Primal-Dual algorithms

Problem	Previous best: $O(\sqrt{\log n})$ apx	Our alg.: $O(\sqrt{\log n})$ apx	Our alg.: $O(\log n)$ apx
Undirected Sparsest Cut	$\tilde{O}(n^2)$ [AHK'04]	$\tilde{O}(n^2)$	$\tilde{O}(m + n^{1.5})$
Undirected Balanced Sep.	$\tilde{O}(n^2)$ [AHK'04]	$\tilde{O}(n^2)$	$\tilde{O}(m + n^{1.5})$
Directed Sparsest Cut	$\tilde{O}(n^{4.5})$	$\tilde{O}(m^{1.5} + n^{2+\varepsilon})$	$\tilde{O}(m^{1.5})$
Directed Balanced Sep.	$\tilde{O}(n^{4.5})$	$\tilde{O}(m^{1.5} + n^{2+\varepsilon})$	$\tilde{O}(m^{1.5})$
Min UnCut	$\tilde{O}(n^{4.5})$	$\tilde{O}(n^3)$	---
Min 2CNF Deletion	$\tilde{O}(n^{4.5})$	$\tilde{O}(nm^{1.5} + n^3)$	---



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Min UnCut	$\tilde{O}(n^{4.5})$	$\tilde{O}(n^3)$	---
Min 2CNF Deletion	$\tilde{O}(n^{4.5})$	$\tilde{O}(nm^{1.5} + n^3)$	---

Cannot be achieved by LPs even!

# Our Results: Near-linear time algorithm for Max Cut

- $\tilde{O}(n + m)$  time algorithm to approximate Max Cut SDP to  $(1 + o(1))$  factor
- Previous best:  $\tilde{O}(n^2)$  time algorithm by Klein, Lu '95

# Prototype MW for LPs: Winnow [L'88]

$$\begin{aligned} a_1 \cdot x &\geq -\delta \\ a_2 \cdot x &\geq -\delta \\ &\vdots \\ a_m \cdot x &\geq -\delta \\ x &\geq 0 \\ \sum_i x_i &= 1 \end{aligned}$$

Thm: Finds  $x$  in  $O(\rho^2 \log(n)/\delta^2)$  iterations.

$$\rho = \max_{ij} |a_{ij}|$$

MW for LP:

Init:  $x = (1/n, \dots, 1/n)$

Update:

$$x_j = x_j \cdot \exp(-\varepsilon a_{ij}) / \Phi$$

$\Phi = \text{norm. factor}$

MW algorithm: boosting, hard-core sets, zero-sum games, flows, portfolio, ...

$x$

Oracle

Find  $i$  s.t.  $a_i \cdot x < -\delta$

$a_i$

Convex comb. of constraints allowed:  
 $\sum_i \gamma_i a_i \cdot x < -\delta$ , where  $\gamma_i \geq 0$ ,  $\sum_i \gamma_i = 1$ .  
Hence Primal-Dual.

# Prototype Matrix MW for SDPs

$$\begin{aligned} A_1 \bullet X &\geq -\delta \\ A_2 \bullet X &\geq -\delta \\ &\vdots \\ A_m \bullet X &\geq -\delta \\ X &\succeq 0 \\ \text{Tr}(X) &= 1 \end{aligned}$$

Thm: Finds  $X$  in  $O(\rho^2 \log(n)/\delta^2)$  iterations.

$$\rho = \max_i \|A_i\|$$

Matrix MW for SDP:

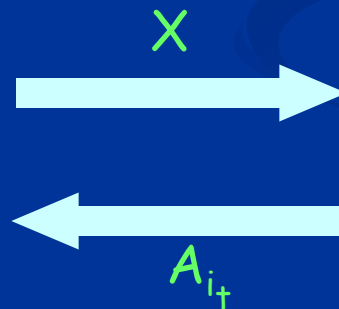
Init:  $X = I/n$

Update:

$$X = \exp(-\varepsilon \sum_{s=1}^t A_{i_s}) / \Phi$$

$\Phi = \text{norm. factor}$

Analysis uses  $\Phi$   
as potential fn.



Oracle  
Find  $i_t$  s.t.  $A_{i_t} \bullet X < -\delta$

Convex comb. of constraints allowed:  
 $\sum_i \gamma_i A_i \bullet X < -\delta$ , where  $\gamma_i \geq 0$ ,  $\sum_i \gamma_i = 1$ .  
Hence Primal-Dual.

# The Matrix Exponential

- Matrix exponential:  
 $\exp(A) = I + A + A^2/2! + A^3/3! + \dots$
- Always PSD:  $\exp(A) \succeq 0$
- Golden-Thompson inequality:  
 $\text{Tr}(\exp(A+B)) \leq \text{Tr}(\exp(A)\exp(B))$
- Computation:
  - $O(n^3)$  time
  - Usually, can use J-L lemma
  - Only need  $\exp(A)v$  products:  
 $\tilde{O}(m)$  time

Matrix MW for SDP:

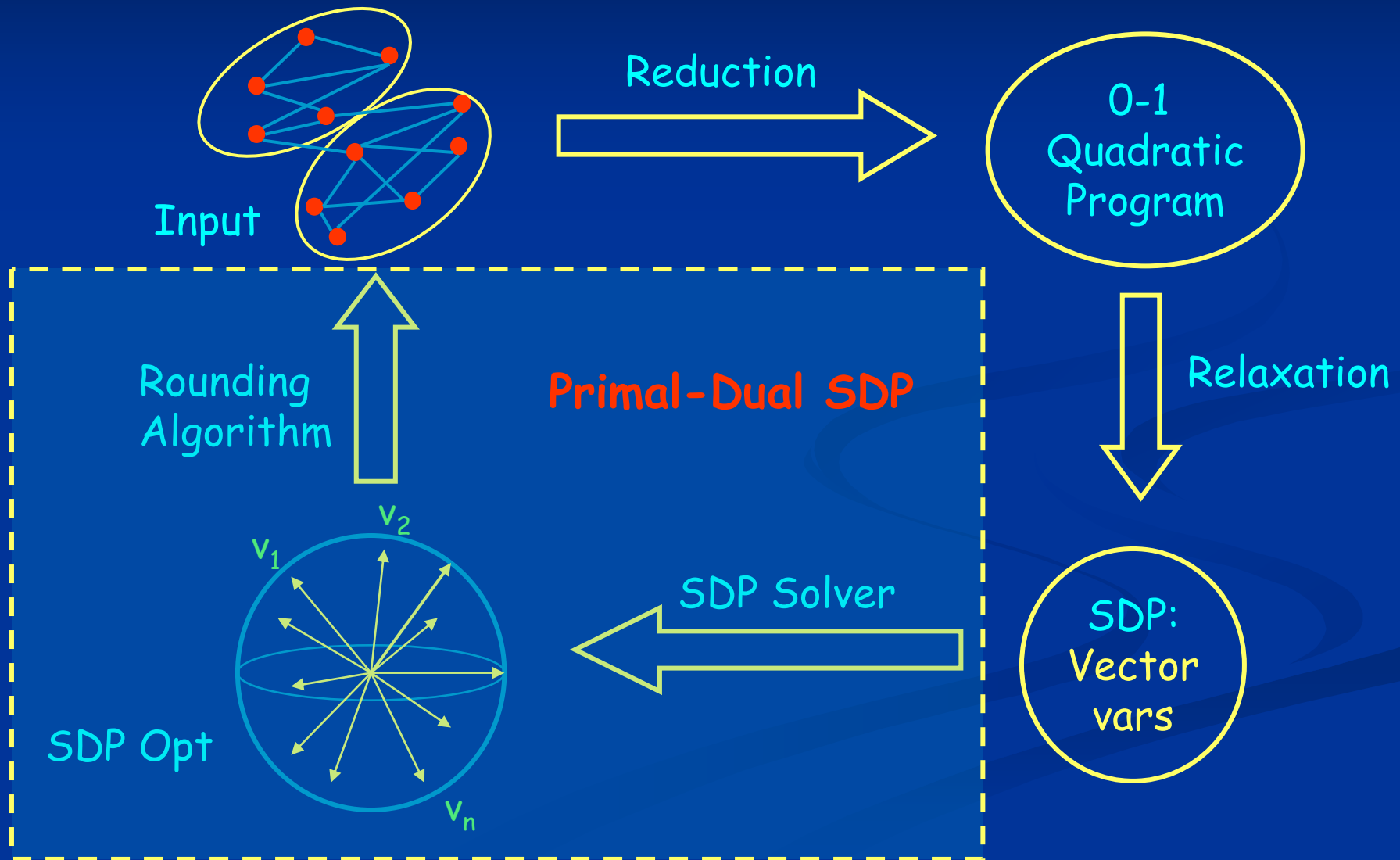
Init:  $X = I/n$

Update:

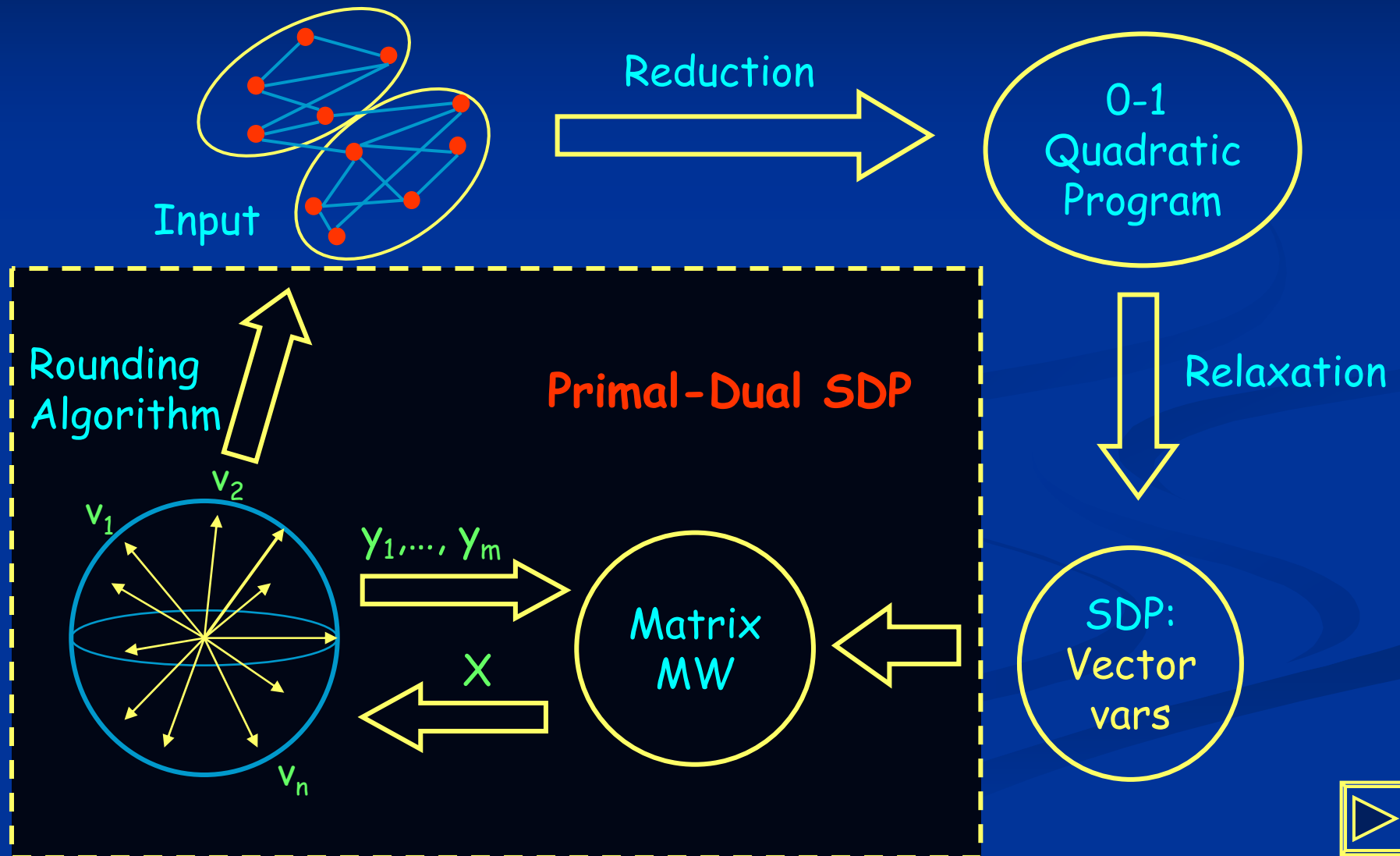
$$X = \exp(-\varepsilon \sum_{s=1}^t A_{i_s}) / \Phi$$

$\Phi = \text{norm. factor}$

# Approximation via SDP Relaxations

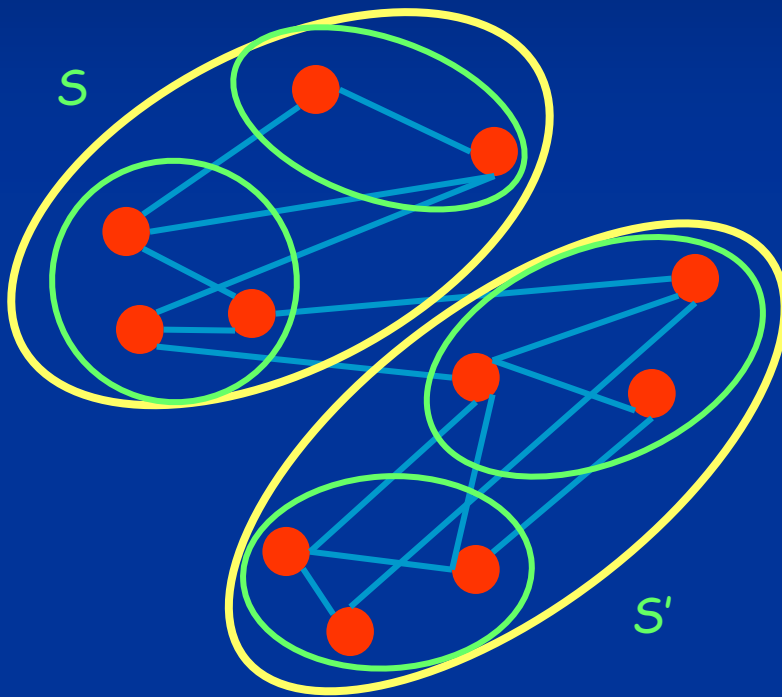


# Primal-Dual SDP Framework



# Approximating Balanced Separator

$G = (V, E)$



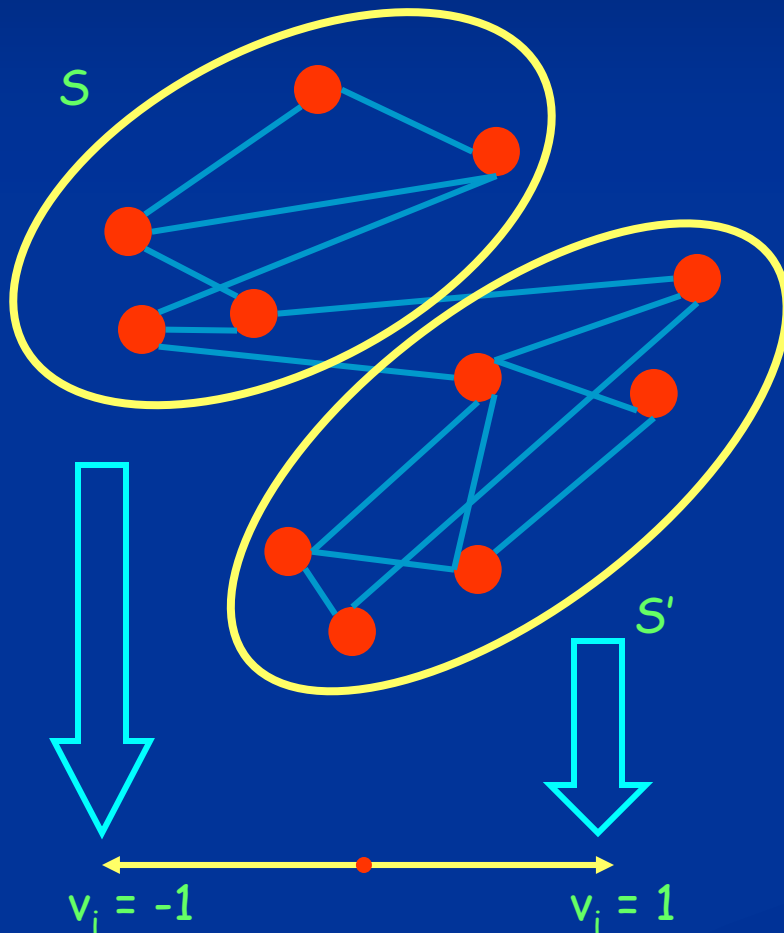
- Cut  $(S, S')$  is  $c$ -balanced if  $|S|, |S'| \geq cn$
- Min  $c$ -Balanced Separator:  $c$ -balanced cut of min capacity
- Numerous applications:
  - Divide-and-conquer algorithms
  - Markov chains
  - Geometric embeddings
  - Clustering
  - Layout problems
  - ...



# SDP for Balanced Separator

$G = (V, E)$

$$\frac{1}{4} \|v_i - v_j\|^2 = 0 \text{ if } i, j \text{ on same side,} \\ = 1 \text{ otherwise}$$



SDP:

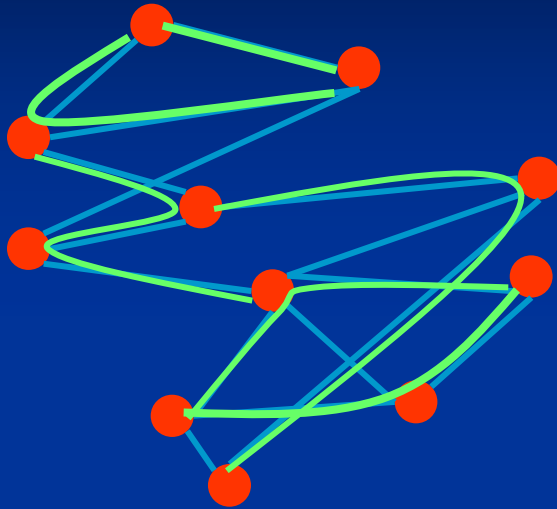
$$\min \sum_{i,j \in E} \frac{1}{4} \|v_i - v_j\|^2$$

$$\forall i: \|v_i\|^2 = 1$$

$$\forall ijk: \|v_i - v_j\|^2 + \|v_j - v_k\|^2 \geq \|v_i - v_k\|^2$$

$$\sum_{i,j} \frac{1}{4} \|v_i - v_j\|^2 \geq c(1-c)n^2$$

# Implementing Oracle



Primal:  
$$\min \sum_{i,j \in E} \frac{1}{4} \|v_i - v_j\|^2$$

$$\forall i: \|v_i\|^2 = 1$$

$$\forall ijk: \|v_i - v_j\|^2 + \|v_j - v_k\|^2 \geq \|v_i - v_k\|^2$$

$$\sum_{i,j} \frac{1}{4} \|v_i - v_j\|^2 \geq c(1-c)n^2$$

Thm: Given  $v_i, \alpha$ :

1. Max-flow  $\Rightarrow$  desired flow or cut of value  $O(\log(n) \cdot \alpha)$ .
2. Multicommodity flow  $\Rightarrow$  desired flow or cut of value  $O(\sqrt{\log(n)} \cdot \alpha)$ .

# Conclusions and Future Work

- Matrix MW algorithm: more applications in
  - Solving SDPs: e.g. Min Linear Arrangement
  - Quantum algorithms: density matrix is a central concept
  - Learning: e.g. online variance minimization [WK COLT'06], online PCA [WK NIPS'06]
  - Other applications?
- Linear time algorithm for Sparsest Cut?
  - Our algorithm runs in  $\tilde{O}(m + n^{1.5})$  time for an  $O(\log n)$  approximation

Thank you!