

# On the Consistency of Ranking Algorithms

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# Ranking

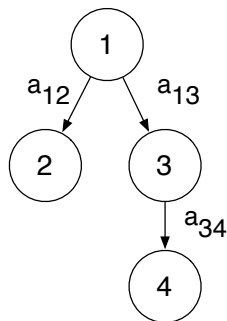
**Goal:** Order set of inputs/results to best match the preferences of an individual or a population

- ▶ Web search: Return most relevant results for user queries
- ▶ Recommendation systems:
  - ▶ Suggest movies to watch based on user's past ratings
  - ▶ Suggest news articles to read based on past browsing history
- ▶ Advertising placement: Maximize profit and click-through

# Supervised ranking setup

**Observe:** Sequence of training examples

- ▶ **Query**  $q$ : e.g., search term
- ▶ Set of **results**  $x$  to rank
  - ▶ Items  $\{1, 2, 3, 4\}$
- ▶ **Weighted DAG**  $G$  representing preferences over results
  - ▶ Item 1 preferred to  $\{2, 3\}$  and item 3 to 4



Example  $G$  with  
 $x = \{1, 2, 3, 4\}$

Observe multiple preference graphs for the same query  $q$  and results  $x$

# Supervised ranking setup

**Learn:** Scoring function  $f(x)$  to rank results  $x$

- ▶ Real-valued score for result  $i$

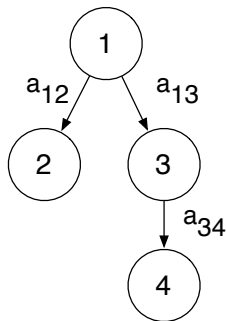
$$s_i := f_i(x)$$

- ▶ Result  $i$  ranked above  $j$  iff  $f_i(x) > f_j(x)$
- ▶ Loss suffered when scores  $s$  disagree with preference graph  $G$ :

$$L(s, G) = \sum_{i,j} a_{ij} \mathbf{1}_{(s_i < s_j)}$$

Example:

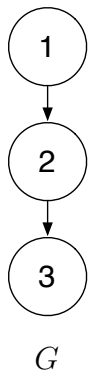
$$L(s, G) = a_{12} \mathbf{1}_{(s_1 < s_2)} + a_{13} \mathbf{1}_{(s_1 < s_3)} + a_{34} \mathbf{1}_{(s_3 < s_4)}$$



Example  $G$  with  
 $x = \{1, 2, 3, 4\}$

# Supervised ranking setup

**Example:** Scoring function  $f$  optimally ranks results in  $G$



$$f_1(x) > f_2(x)$$

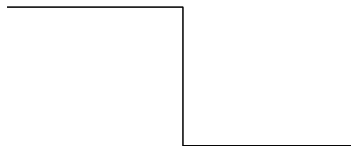
$$f_2(x) > f_3(x)$$

## Detour to classification

Consider the simpler problem of classification

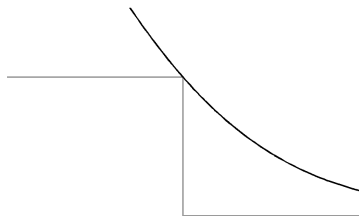
- ▶ Given: Input  $x$ , label  $y \in \{-1, 1\}$
- ▶ Learn: Classification function  $f(x)$ . Have *margin*  $s = yf(x)$

Loss  $L(s) = 1_{(s \leq 0)}$



Hard

Surrogate loss  $\phi(s)$



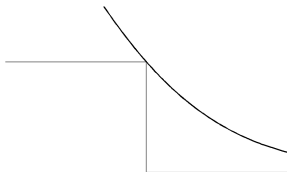
Tractable



# What about ranking consistency?

Minimization of true ranking loss is **hard**

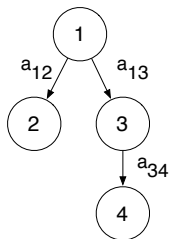
- ▶ Replace ranking loss  $L(s, G)$  with tractable surrogate  $\varphi(s, G)$



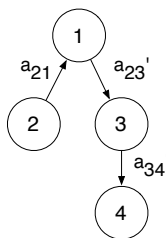
**Question:** When is surrogate minimization consistent for ranking?



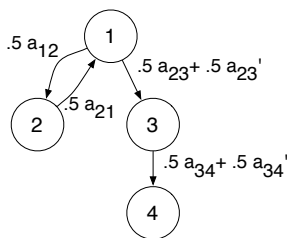
# Conditional losses



$$p(G_1) = .5$$



$$p(G_2) = .5$$



Aggregate

- ▶  $\ell(p, s) = \sum_G p(G|x, q) L(s, G)$
- ▶  $\ell(p, s) = .5 a_{21} 1_{(s_2 < s_1)} + .5(a_{12} + a'_{12}) 1_{(s_1 < s_2)}$   
 $\quad + .5(a_{23} + a'_{23}) 1_{(s_1 < s_3)} + .5(a_{34} + a'_{34}) 1_{(s_3 < s_4)}$
- ▶ Optimal score vectors

$$A(p) = \underset{s}{\operatorname{argmin}} \ell(p, s)$$

# Consistency theorem

**Theorem:** Procedure minimizing  $\varphi$  is asymptotically consistent if and only if

$$\inf_s \left\{ \sum_G p(G) \varphi(s, G) \mid s \notin A(p) \right\} > \inf_s \left\{ \sum_G p(G) \varphi(s, G) \right\}$$

In other words,  $\varphi$  is consistent if and only if minimization gives correct order to the results

**Goal:** Find tractable  $\varphi$  so  $s$  that minimizes

$$\sum_G p(G) \varphi(s, G)$$

minimizes  $\ell(p, s)$ .

# Consistent and Tractable?

Hard to get consistent and tractable  $\varphi$

- ▶ In general, it is NP-hard even to *find*  $s$  minimizing

$$\sum_G p(G) L(s, G).$$

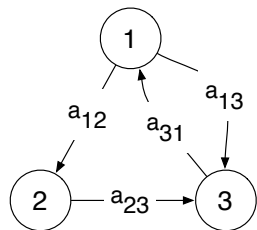
(reduction from feedback arc-set problem)

Some restrictions on the problem space necessary...

# Low noise setting

**Definition:** Low noise if  $a_{ij} - a_{ji} > 0$  and  $a_{jk} - a_{kj} > 0$

implies  $a_{ik} - a_{ki} \geq (a_{ij} - a_{ji}) + (a_{jk} - a_{kj})$



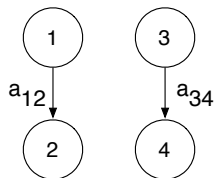
$$a_{13} - a_{31} \geq a_{12} + a_{23}$$

- ▶ Intuition: weight on path reinforces local weights, local weights reinforce paths.
- ▶ Reverse triangle inequality
- ▶ True when DAG derived from user ratings

# Trying to achieve consistency

Try ideas from classification:  $\phi$  is convex, bounded below,  $\phi'(0) < 0$ .  
Common in ranking literature.<sup>2</sup>

$$\varphi(s, G) = \sum_{ij} a_{ij} \phi(s_i - s_j)$$



$$\varphi(s, G) = a_{12} \phi(s_1 - s_2) + a_{34} \phi(s_3 - s_4)$$

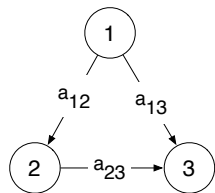
**Theorem:**  $\varphi$  is not consistent, even in low noise settings.

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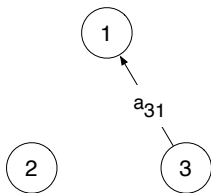
<sup>2</sup>Herbrich et al., 2000; Freund et al., 2003; Dekel et al., 2004, etc.

# What is the problem?

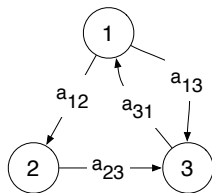
Surrogate loss  $\varphi(s, G) = \sum_{ij} a_{ij} \phi(s_i - s_j)$



$$p(G_1) = .5$$



$$p(G_2) = .5$$



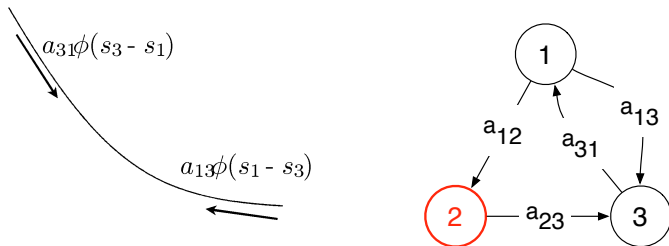
Aggregate

$$\sum_G p(G) \varphi(s, G) = \frac{1}{2} \varphi(s, G_1) + \frac{1}{2} \varphi(s, G_2)$$

$$\propto a_{12} \phi(s_1 - s_2) + a_{13} \phi(s_1 - s_3) + a_{23} \phi(s_2 - s_3) + a_{31} \phi(s_3 - s_1)$$

# What is the problem?

$$a_{12}\phi(s_1 - s_2) + a_{13}\phi(s_1 - s_3) + a_{23}\phi(s_2 - s_3) + a_{31}\phi(s_3 - s_1)$$



More bang for your \$\$ by increasing to 0 from left:  $s_1 \downarrow$ . Result:

$$s^* = \operatorname{argmin}_s \sum_{ij} a_{ij}\phi(s_i - s_j)$$

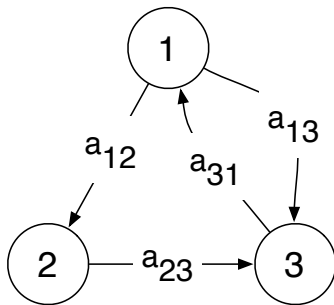
can have  $s_2^* > s_1^*$ , even if  $a_{13} - a_{31} > a_{12} + a_{23}$ .

## Trying to achieve consistency, II

**Idea:** Use margin-based penalty<sup>3</sup>

$$\varphi(s, G) = \sum_{ij} \phi(s_i - s_j - a_{ij})$$

**Inconsistent:** Take  $a_{ij} \equiv c$ ; can reduce to previous case



<sup>3</sup>Shashua and Levin 2002



# Ranking is challenging

- ▶ Inconsistent in general
- ▶ Low noise settings
  - ▶ Inconsistent for edge-based convex losses

$$\varphi(s, G) = \sum_{ij} a_{ij} \phi(s_i - s_j)$$

- ▶ Inconsistent for margin-based convex losses

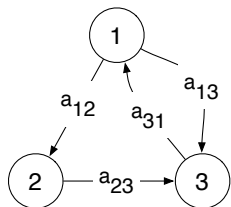
$$\varphi(s, G) = \sum_{ij} \phi(s_i - s_j - a_{ij})$$

- ▶ Question: Do tractable consistent losses exist?

Yes.

# A solution in the low noise setting

Recall reverse triangle inequality



- ▶ Idea 1: make loss reduction proportional to weight difference  $a_{ij} - a_{ji}$
- ▶ Idea 2: regularize to keep loss well-behaved

**Theorem:** For  $r$  strongly convex, following loss is consistent:

$$\varphi(s, G) = \sum_{ij} a_{ij}(s_j - s_i) + \sum_j r(s_j)$$

# Consistency proof sketch

Write surrogate, take derivatives:

$$\sum_G p(G) \varphi(s, G) = \sum_{ij} a_{ij}(s_j - s_i) + \sum_j r(s_j)$$
$$\frac{\partial}{\partial s_i} = \sum_j (a_{ij} - a_{ji}) + r'(s_i) = 0$$

Simply note that  $r'$  is strictly increasing, see that

$$s_i > s_k \quad \Leftrightarrow \quad \sum_j a_{ij} - a_{ji} > \sum_j a_{kj} - a_{jk}$$

Last holds by low-noise assumption.

# Experimental results

- ▶ MovieLens dataset:<sup>4</sup> 100,000 ratings for 1682 movies by 943 users
- ▶ Query is user  $u$ , results  $X = \{1, \dots, 1682\}$  are movies
- ▶ Scoring function:  $f_i(x, u) = w^T \psi(x_i, u)$
- ▶  $\psi$  maps from movie  $x_i$  and user  $u$  to features
- ▶ Per-user pair weight  $a_{ij}^u$  is difference of user's ratings for movies  $x_i, x_j$

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<sup>4</sup>GroupLens Lab, 2008

# Surrogate risks

Losses based on pairwise comparisons

$$\text{Ours} \quad \sum_{i,j,u} a_{ij}^u w^T (\psi(x_j, u) - \psi(x_i, u)) + \theta \sum_{i,u} (w^T \psi(x_i, u))^2$$

$$\text{Hinge} \quad \sum_{i,j,u} a_{ij}^u [1 - w^T (\psi(x_j, u) - \psi(x_i, u))]_+$$

$$\text{Logistic} \quad \sum_{i,j,u} a_{ij}^u \log \left( 1 + e^{w^T (\psi(x_j, u) - \psi(x_i, u))} \right)$$

# Experimental results

Test losses for each surrogate (standard error in parenthesis)

Num training pairs	Hinge	Logistic	Ours
20000	.478 (.008)	.479 (.010)	<b>.465</b> (.006)
40000	.477 (.008)	.478 (.010)	<b>.464</b> (.006)
80000	.480 (.007)	.478 (.009)	<b>.462</b> (.005)
120000	.477 (.008)	.477 (.009)	<b>.463</b> (.006)
160000	.474 (.007)	.474 (.007)	<b>.461</b> (.004)

# Conclusions

- ▶ General theorem for consistency of ranking algorithms
- ▶ General inconsistency results as well as inconsistency results for several natural and commonly used losses, even in low noise settings
- ▶ Consistent loss for low noise settings

# Open questions

- ▶ What are appropriate ranking losses? Click-based loss, ratings-based losses?
- ▶ Other consistent losses?
- ▶ Convergence rates?